

## Nowak project

### 1. Linear case:

$$x_1' = (1 - q) \sum_{n \geq 1} a_n x_n - (qa_1 + d_1) x_1$$

$$x_n' = qa_{n-1} x_{n-1} - (qa_n + d_n) x_n.$$

$$y' = by - dy.$$

Eigenvalue condition for the  $x$  equation:

$$1 = \frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qa_k}{(\lambda + (qa_k + d_k))} \quad (1.1)$$

Note that  $\lambda > 0$  requires that

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qa_k}{(qa_k + d_k)} \geq 1 \quad (1.2)$$

The condition  $\lambda > b - d$  is needed for growth faster than that of  $y$ . This condition reads

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qa_k}{(b-d + (qa_k + d_k))} > 1. \quad (1.3)$$

In the case when  $a_k = a$  and  $d_k = d$  is constant, then the condition in (1.1) asserts that  $1 = \frac{1-q}{q} \sum_{n \geq 1} \eta^n$  with  $\eta = qa(\lambda + qa + d)^{-1}$ . This is to say that  $\frac{q}{1-q} = \eta/(1-\eta)$  and so  $\eta = q$ . Thus,  $\lambda + qa + d = 2qa$  and so  $\lambda = (1-q)a - d$ . Growth faster than the  $y$ -model requires  $(1-q)a > b$  which is maybe expected.

Martins 'system with food' on page 2 at equilibrium  $z^* = d/b$  gives the linear instability condition that is identical to (1.2) with the replacement  $q \rightarrow z^*q$ . This understood, I will address the remaining questions on the bottom of page 2 with  $z^* = 1$ .

#### a) Neutrality

Martin suggests considering the case  $d_k = d$  in which case the condition  $\lambda = b - d$  reads

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qa_k}{(qa_k + b)} = 1. \quad (1.4)$$

Martin claims that this condition is obeyed if  $a_k = kb$ . In the latter case, the condition in (1.4) reads

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qk}{(qk+1)} = 1 . \quad (1.5)$$

To verify that this is indeed the case, introduce for the moment  $\eta$  to denote  $1/q$ . What is written in (1.5) is equivalent to the assertion that

$$\sum_{n \geq 1} \prod_{k=1}^n \frac{k}{(k+\eta)} = \frac{1}{\eta-1} . \quad (1.6)$$

A given term in this sum is equal to

$$\eta \int_0^{\infty} \frac{t^n}{(1+t)^{n+1+\eta}} dt . \quad (1.7)$$

as can be seen using  $n$  successive integration by parts. This being the case, interchange the sum and the integral. The result on the left side of (1.6) is then

$$\eta \int_0^{\infty} \frac{t}{(1+t)^{2+\eta}} \sum_{n \geq 0} \left(\frac{t}{1+t}\right)^n dt . \quad (1.8)$$

The sum in the integrand is geometric, and what is written above is equal

$$\eta \int_0^{\infty} \frac{t}{(1+t)^{1+\eta}} dt = \int_0^{\infty} \frac{1}{(1+t)^{\eta}} dt . \quad (1.9)$$

The right hand integral is indeed equal to  $\frac{1}{\eta-1}$  .

**b)  $a_k = b$  for  $k < m$  and  $a_k = a$  for  $k > m$**

Martin asks for the case  $a_k = b$  for  $k < m$  and  $a_k = a$  for  $k \geq m$  with  $a > b$ . I assume again that all  $d_k = d$ . In this case, the left hand side of (1.4) reads

$$\frac{1-q}{q} \sum_{1 \leq n < m} \left(\frac{q}{(q+1)}\right)^n + \left(\frac{qa}{(qa+b)}\right)^m \sum_{k \geq 0} \left(\frac{qa}{(qa+b)}\right)^k , \quad (1.10)$$

Evaluating these sums gives the instability condition

$$\left(\frac{qa}{(qa+b)}\right)^{m-1} \frac{a}{b} - \left(\frac{q}{(q+1)}\right)^{m-1} > \frac{q}{1-q} . \quad (1.11)$$

**c)  $a_k$  is a rational function of  $k$**

The next case Martin asks about is that where  $a_k = (c_0 k - c_1)/(k + c_2)$  where the constants are chose so that  $b = (c_0 - c_1)/(1 + c_2)$ . The neutrality condion in (1.4) reads

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{q(c_0 k - c_1)}{(qc_0 + b)k + (bc_2 - qc_1)} = 1 . \quad (1.12)$$

This can be rewritten as

$$\frac{1-q}{q} \sum_{n \geq 1} \gamma^n \prod_{k=1}^n \frac{k - \alpha}{k + \beta} = 1 , \quad (1.13)$$

where  $\gamma = \frac{qc_0}{qc_0 + b}$ ,  $\alpha = \frac{c_1}{qc_0}$ , and  $\beta = \frac{bc_2 - qc_1}{qc_0 + b}$ . The n'th term in the sum in (1.13) can be written as

$$\rho^{-1} \int_0^{\infty} \frac{t^{n-\alpha}}{(1+t)^{n+1+\beta}} dt \quad \text{where} \quad \rho = \int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{1+\beta}} dt . \quad (1.14)$$

This understood, interchange the integral with the sum to rewrite the sum in (1.13) as

$$\gamma \rho^{-1} \int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{1+\beta}} \sum_{n \geq 0} \left( \frac{\gamma t}{1+t} \right)^n dt = \gamma \rho^{-1} \int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{\beta} (1+(1-\gamma)t)} dt . \quad (1.15)$$

The stability condition in (1.12) can be restated as

$$\frac{qc_0}{qc_0 + b} \int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{\beta} (1+(1-\gamma)t)} dt > \frac{q}{1-q} \int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{1+\beta}} dt . \quad (1.16)$$

According to Gradshteyn and Ryzhik, (*Tables of integrals, series and products; Enlarged edition*, I. S. Gradshteyn and I. M. Rhyzik; Academic Press 1980), these definite integrals can be expressed in terms of two special functions, these denoted by B (this being the 'beta function' or 'Euler's integral of the first kind') and F (this being 'Gauss' hypergeometric function'). In particular, Equation 9 in Section 3.197 writes

- $\int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{\beta} (1+(1-\gamma)t)} dt = (1-\gamma)^{\alpha+\beta-1} B(\alpha+\beta, 1-\alpha) F(\beta, \alpha+\beta; 1+\beta; \gamma).$
- $\int_0^{\infty} \frac{t^{-\alpha}}{(1+t)^{1+\beta}} dt = B(\alpha+\beta, 1-\alpha) F(\beta, \alpha+\beta; 1+\beta; 0) .$

(1.17)

For what it is worth, the special functions B and F are defined respectively in Sections 8.38 and 9.10-13 of Gradshteyn and Ryzhik.

**d) Interpreting the instability condition**

Martin asks for the meaning of the condition that

$$\frac{1-q}{q} \sum_{n \geq 1} \prod_{k=1}^n \frac{qa_k}{(qa_k + b)} > 1. \quad (1.18)$$

Setting  $\alpha_k = \frac{qa_k}{(qa_k + b)}$ , this is equivalent to the condition that

$$\alpha_1 + \alpha_1\alpha_2 + \alpha_1\alpha_2\alpha_3 + \cdots > \frac{q}{1-q}. \quad (1.19)$$

What follows is a thought about an interpretation: Looking at the equation for  $x_{k>1}$ , I can think of  $\alpha_{k-1}$  as the probability of creating some  $x_k$  given  $x_{k-1}$ . This understood,  $\alpha_1$  is the probability of having  $x_2$  given  $x_1$ , then  $\alpha_1\alpha_2$  is the probability of  $x_3$  given  $x_1$  and  $\alpha_1\alpha_2\alpha_3$  is the probability of  $x_4$  given  $x_1$ , etc. The sum on the right can be thought of as a sum of conditional probabilities.

I shall think more about this as a path to an interpretation of (1.19).

**e) Other forms of density regulation**

I haven't had time to consider these yet.